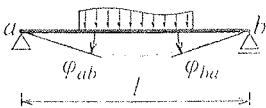
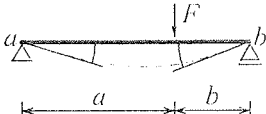
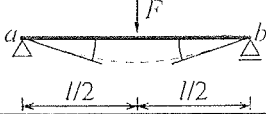
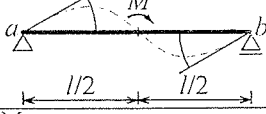
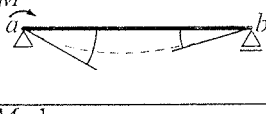
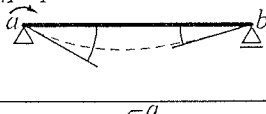
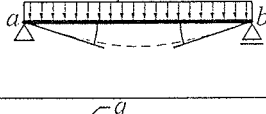
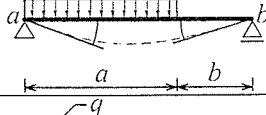
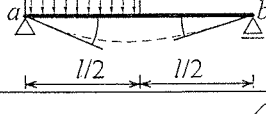
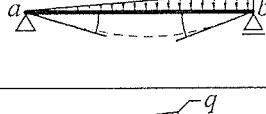
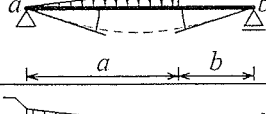
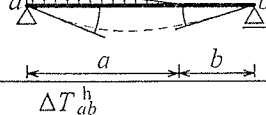
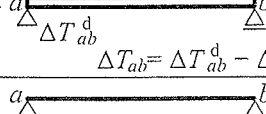
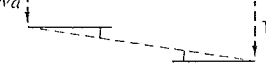


Tabulka 5.2 Pootočení u prostého nosníku konstantní ohybové tuhosti

Pootočení φ_{ab} podporového průřezu a		Pootočení φ_{ba} podporového průřezu b
$\varphi_{ab}^F = \frac{1}{6} \frac{F}{EI} \frac{ab}{l} (l+b)$ (5.8a)		$\varphi_{ba}^F = \frac{1}{6} \frac{F}{EI} \frac{ab}{l} (l+a)$ (5.8b)
$\varphi_{ab}^F = \frac{1}{16} \frac{F}{EI} l^2$ (5.9a)		$\varphi_{ba}^F = \frac{1}{16} \frac{F}{EI} l^2$ (5.9b)
$\varphi_{ab}^M = -\frac{1}{6} \frac{M}{EI} \frac{1}{l} (l^2 - 3b^2)$ (5.10a)		$\varphi_{ba}^M = \frac{1}{6} \frac{M}{EI} \frac{1}{l} (l^2 - 3a^2)$ (5.10b)
$\varphi_{ab}^M = -\frac{1}{24} \frac{M}{EI} l$ (5.11a)		$\varphi_{ba}^M = \frac{1}{24} \frac{M}{EI} l$ (5.11b)
$\varphi_{ab}^M = \frac{1}{3} \frac{M}{EI} l$ (5.12a)		$\varphi_{ba}^M = \frac{1}{6} \frac{M}{EI} l$ (5.12b)
$\alpha_{ab} = \frac{1}{3} \frac{l}{EI}$ (5.13a)		$\beta_{ba} = \frac{1}{6} \frac{l}{EI}$ (5.13b)
$\varphi_{ab}^q = \frac{1}{24} \frac{q}{EI} l^3$ (5.14a)		$\varphi_{ba}^q = \frac{1}{24} \frac{q}{EI} l^3$ (5.14b)
$\varphi_{ab}^q = \frac{1}{24} \frac{q}{EI} \frac{a^2}{l} (2l-a)^2$ (5.15a)		$\varphi_{ba}^q = \frac{1}{24} \frac{q}{EI} \frac{a^2}{l} (2l^2 - a^2)$ (5.15b)
$\varphi_{ab}^q = \frac{9}{384} \frac{q}{EI} l^3$ (5.16a)		$\varphi_{ba}^q = \frac{7}{384} \frac{q}{EI} l^3$ (5.16b)
$\varphi_{ab}^q = \frac{7}{360} \frac{q}{EI} l^3$ (5.17a)		$\varphi_{ba}^q = \frac{8}{360} \frac{q}{EI} l^3$ (5.17b)
$\varphi_{ab}^q = \frac{1}{360} \frac{q}{EI} \frac{a^2}{l} (40l^2 - 45al + 12a^2)$ (5.18a)		$\varphi_{ba}^q = \frac{1}{90} \frac{q}{EI} \frac{a^2}{l} (5l^2 - 3a^2)$ (5.18b)
$\varphi_{ab}^q = \frac{1}{360} \frac{q}{EI} \frac{a^2}{l} (20l^2 - 15al + 3a^2)$ (5.19a)		$\varphi_{ba}^q = \frac{1}{360} \frac{q}{EI} \frac{a^2}{l} (10l^2 - 3a^2)$ (5.19b)
$\varphi_{ab}^T = \frac{1}{2} \alpha_T \Delta T_{ab} \frac{l}{h}$ (5.20a)		$\varphi_{ba}^T = \frac{1}{2} \alpha_T \Delta T_{ab} \frac{l}{h}$ (5.20b)
$\varphi_{ab}^w = \frac{w_b - w_a}{l}$ (5.21a)		$\varphi_{ba}^w = \frac{w_a - w_b}{l}$ (5.21b)